

# Meta-Learning of Structured Representation by Proximal Mapping

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# Motivation

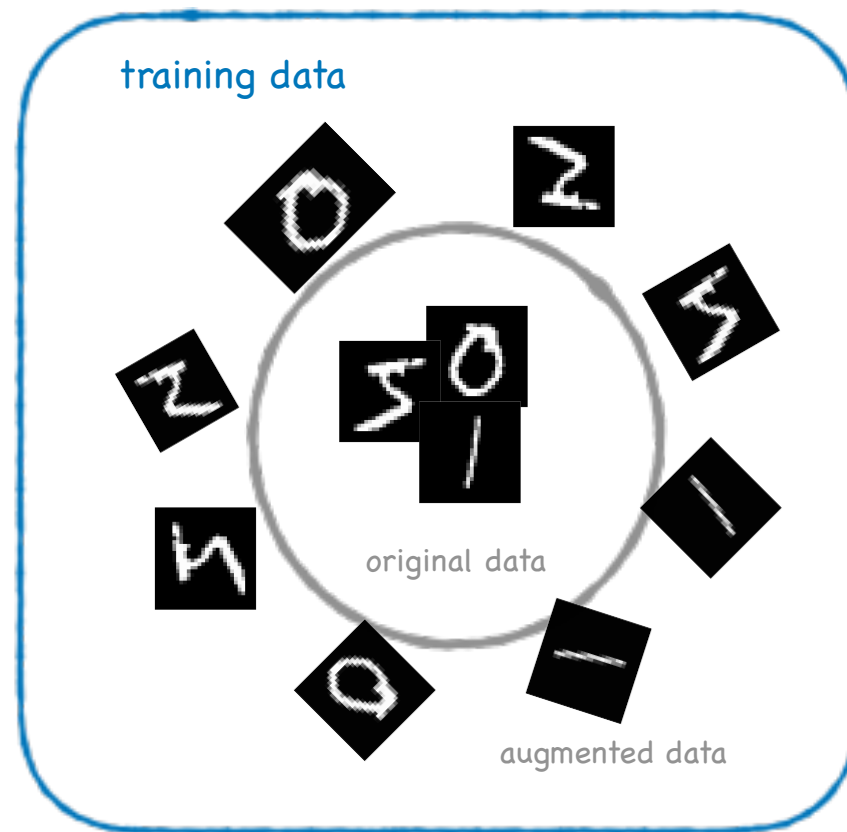
Goal of meta-learning: Extract **prior structures** from a set of **tasks** that allows efficient learning of **new tasks**.

Examples of structural regularities:

- Instance level
  - **Input layers**: transformation beyond group-based diffeomorphism
  - **Within layers**: sparsity, disentanglement, spatial invariance, structured gradient accounting for data covariance, manifold smoothness
  - **Between layers**: equivariance, contractivity, robustness under dropout and adversarial perturbations of preceding nodes
- Batch/Dataset level
  - multi-view, multi-modality, multi-domain
  - diversity, fairness, privacy, causal structure

# Existing Approaches

- Data Augmentation

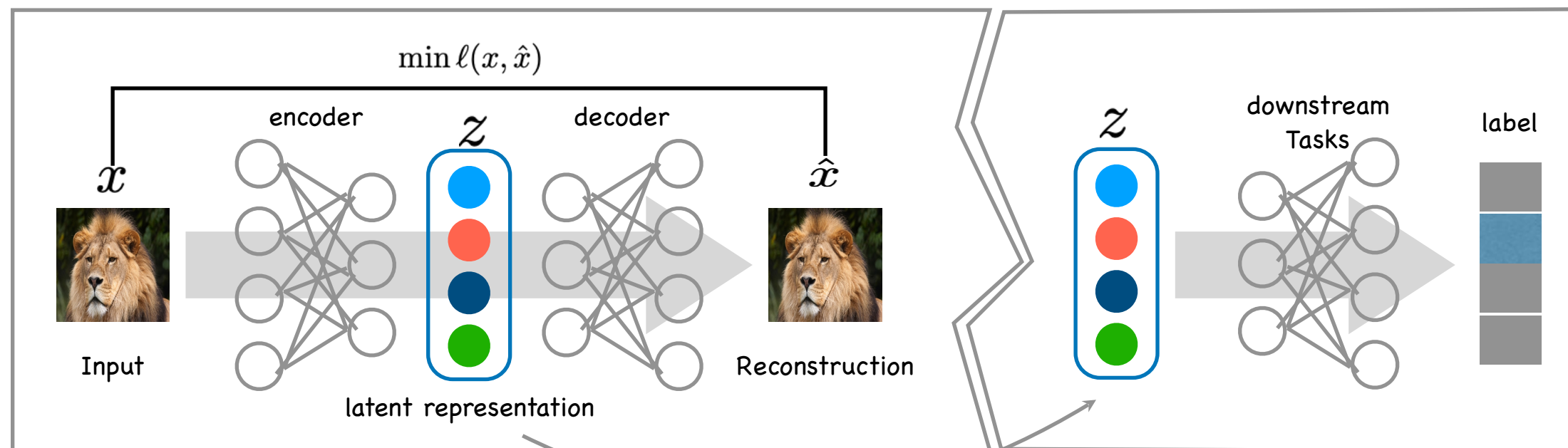


✓ boost prediction performance

× unclear the improvement is due to the **learned representation** or due to a **better classifier**.

# Existing Approaches

## ● Auto-encoder



✓ learned the most salient features

× usually used as an initialization for subsequent supervised task

× not amendable to **end-to-end** learning

**Our goal:** learn **representations** that **explicitly** encode structural priors in an **end-to-end** fashion.

# Existing Approaches

- Regularization

$$\min_f \text{Empirical\_Risk}(f) + R(f)$$

- ✓ simple and efficient

- × contention of **weights** between regularizer and supervised performance

# Proposed Method

Morph a representation  $\mathbf{z}$  towards a structured one by proximal mapping:

promote desired structure

$$z \mapsto \operatorname{argmin}_{x \in \mathcal{C}} \frac{\lambda}{2} \|x - z\|^2 + L(x)$$

$z$ : mini-batch or single-example

a mini-batch  $\longleftrightarrow$  a task in meta-learning

proximal mapping  $\longleftrightarrow$  task-specific base learner

Embed the proximal mapping as a layer into deep networks

## Advantages

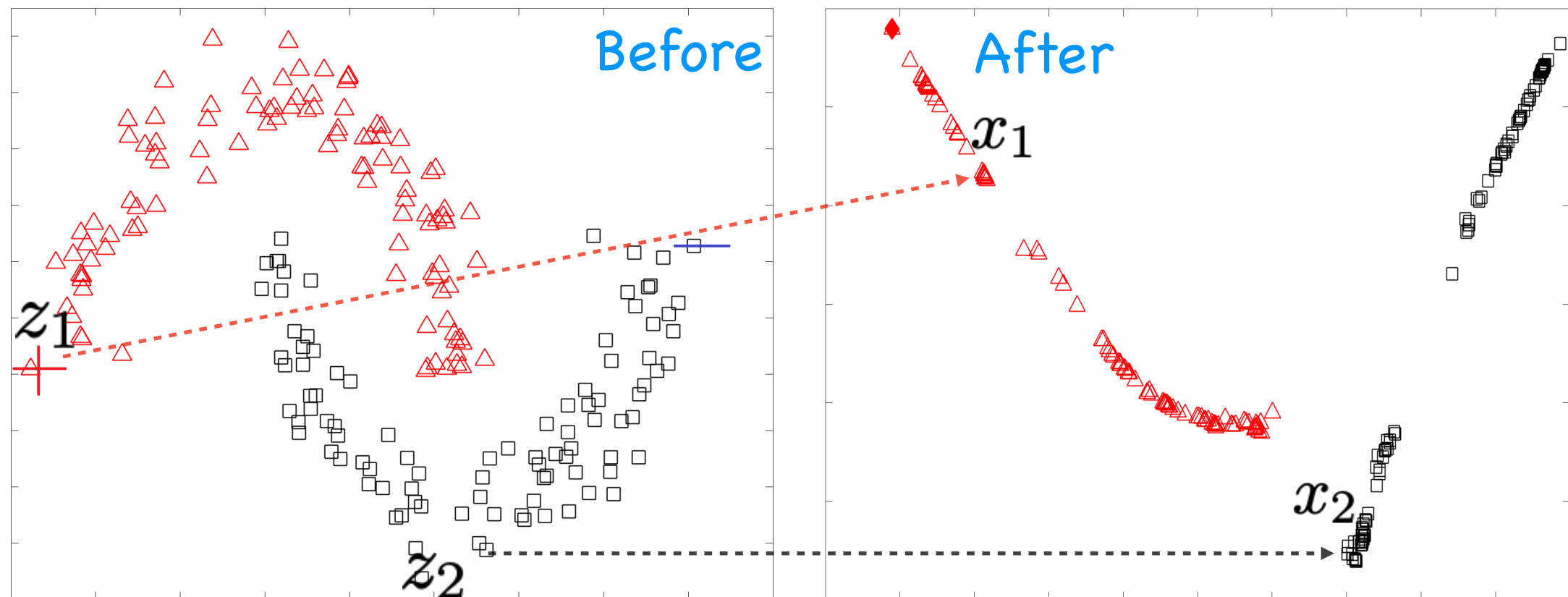
- + decoupling the regularization and supervised learning
- + extend meta-learning to unsupervised base learners

# Proposed Method

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$L$ : graph-Laplacian (for smoothness on manifold)

# MetaProx for Multi-view Learning

In multiview learning, observations are available as pairs of views:  $\{x_i, y_i\}$ .

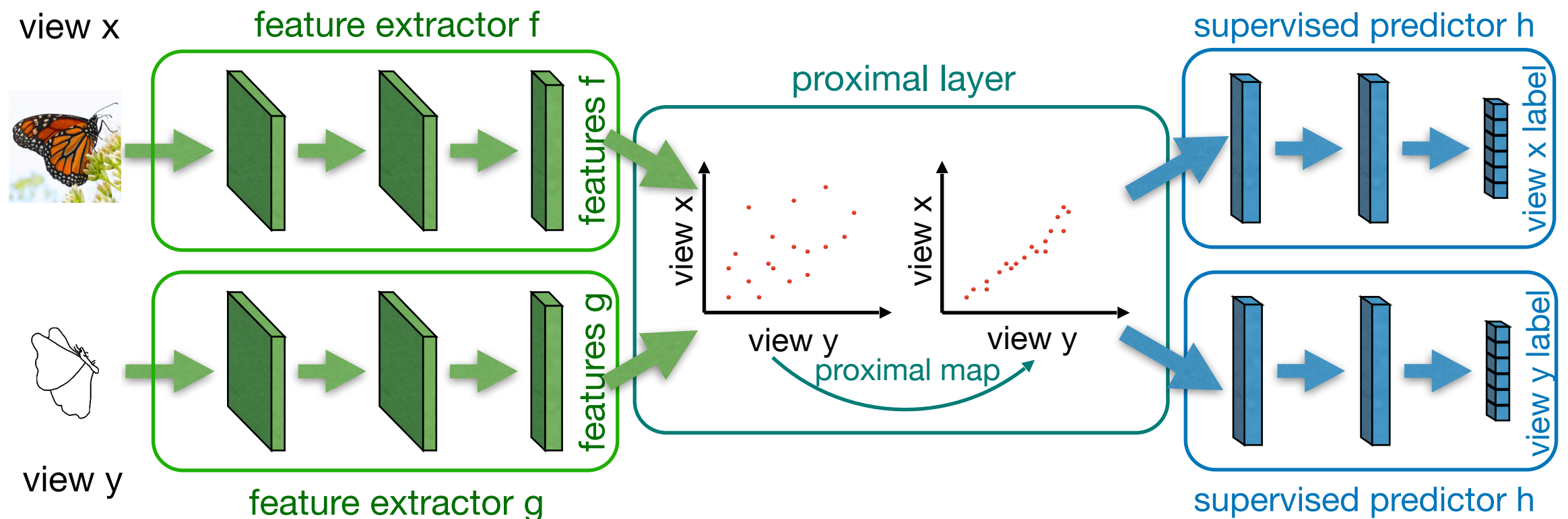
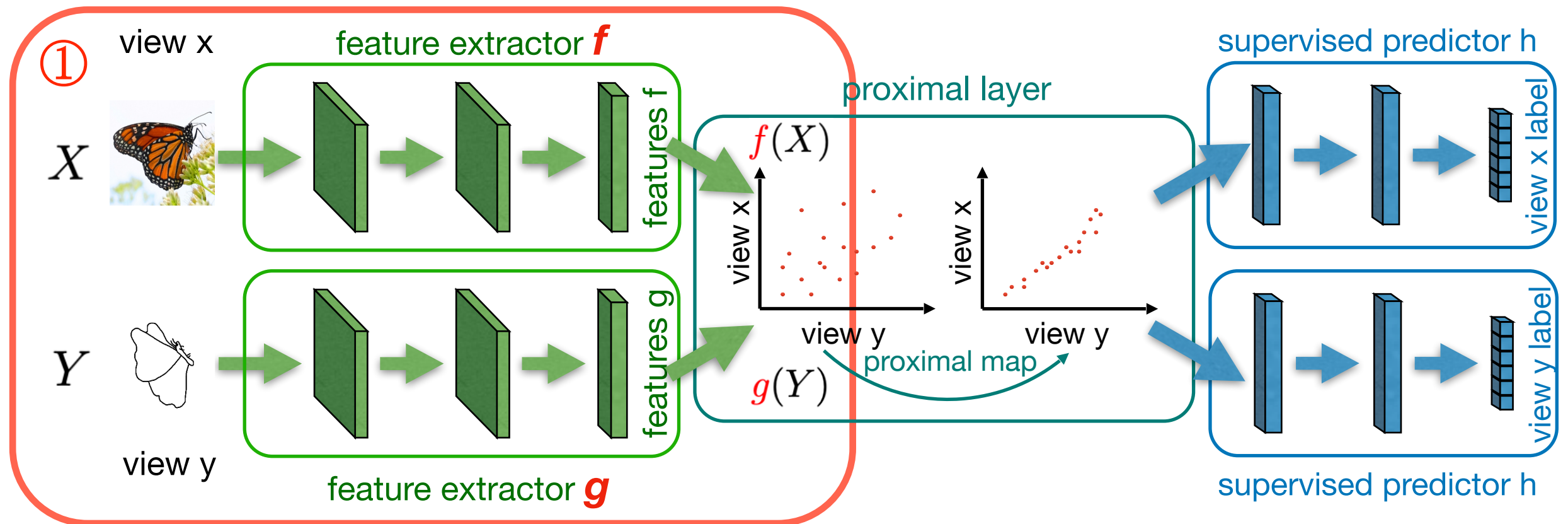


Figure 1: training framework of MetaProx



# MetaProx for Multi-view Learning

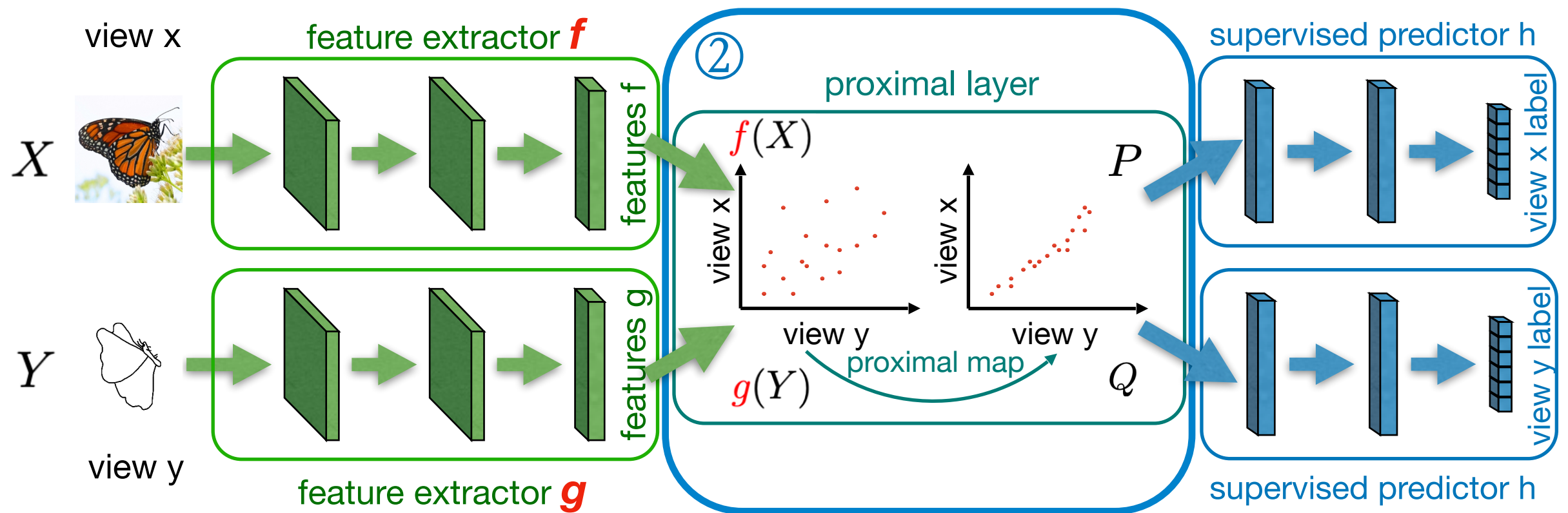


① feature extraction:

$$X \longrightarrow f(X)$$

$$Y \longrightarrow g(Y)$$

# MetaProx for Multi-view Learning

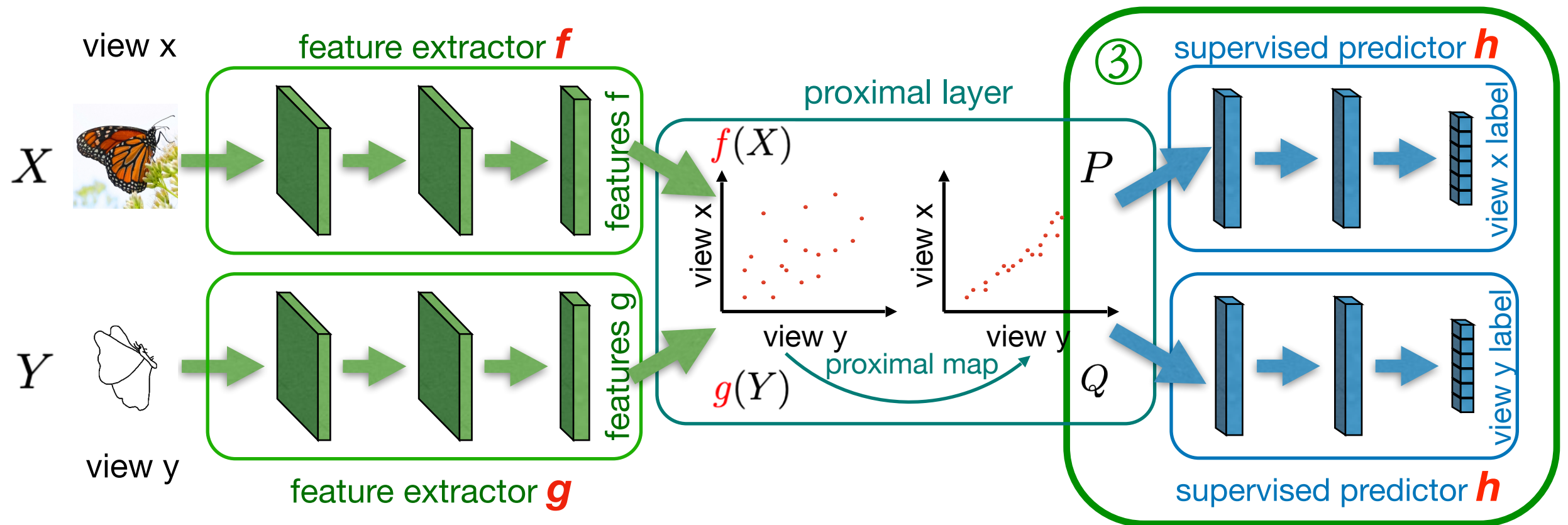


② proximal mapping: promote high correlation between two views

$$\arg \min_{P, Q} \frac{1}{2} \|P - f(X)\|^2 + \frac{1}{2} \|Q - g(Y)\|^2 + \text{CCA}(P, Q)$$

$$\begin{aligned} \text{CCA}(P, Q) &:= \min_{U, V} -\text{tr}(U^\top P Q^\top V), \\ \text{s.t. } &U^\top P P^\top U = I \\ &V^\top Q Q^\top V = I \\ &u_i^\top P Q^\top v_j = 0, \forall i \neq j \text{ from } 1 \text{ to } k. \end{aligned}$$

# MetaProx for Multi-view Learning

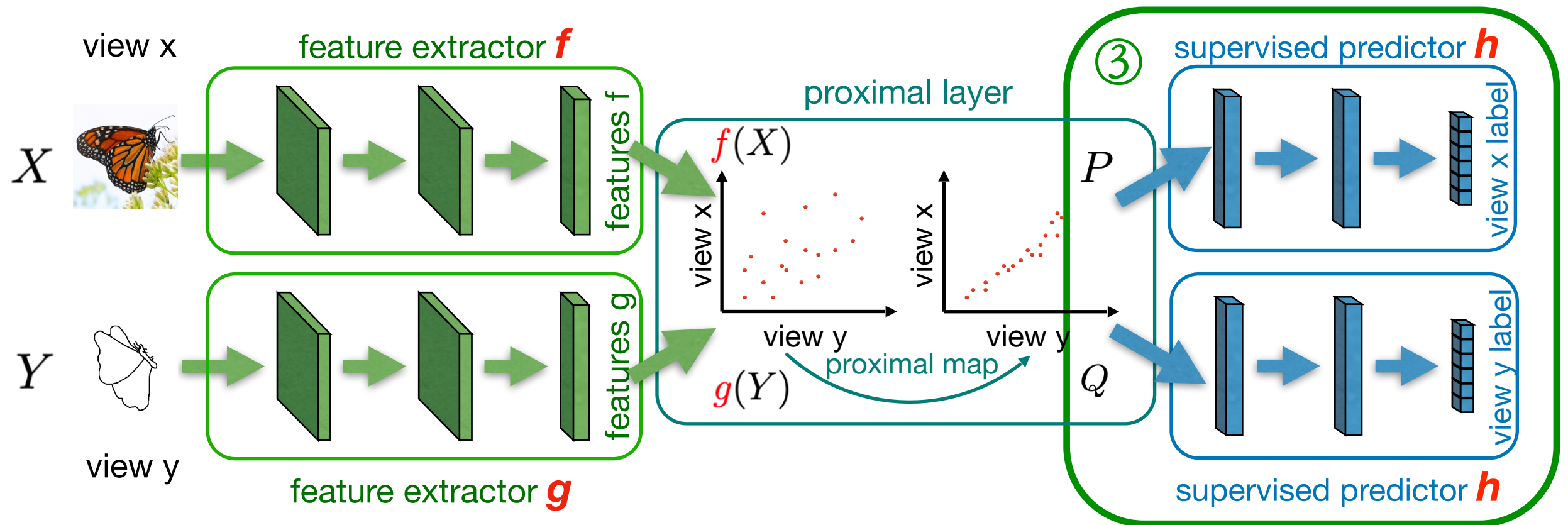


## ③ supervised task

$$\min_{f,g,h} \text{loss} \left( h \left( \begin{array}{l} \arg \min_{P,Q} \frac{1}{2} \|P - f(X)\|^2 \\ + \frac{1}{2} \|Q - g(Y)\|^2 \\ + \text{CCA}(P, Q) \end{array} \right), \text{ground true label} \right)$$

$h$ : supervised predictor

# MetaProx for Multi-view Learning



## ③ supervised task

$$\min_{f,g,h} \text{loss} \left( h \left( \begin{array}{l} \arg \min_{P,Q} \frac{1}{2} \|P - f(X)\|^2 \\ + \frac{1}{2} \|Q - g(Y)\|^2 \\ + \text{CCA}(P, Q) \end{array} \right), \text{ground true label} \right)$$

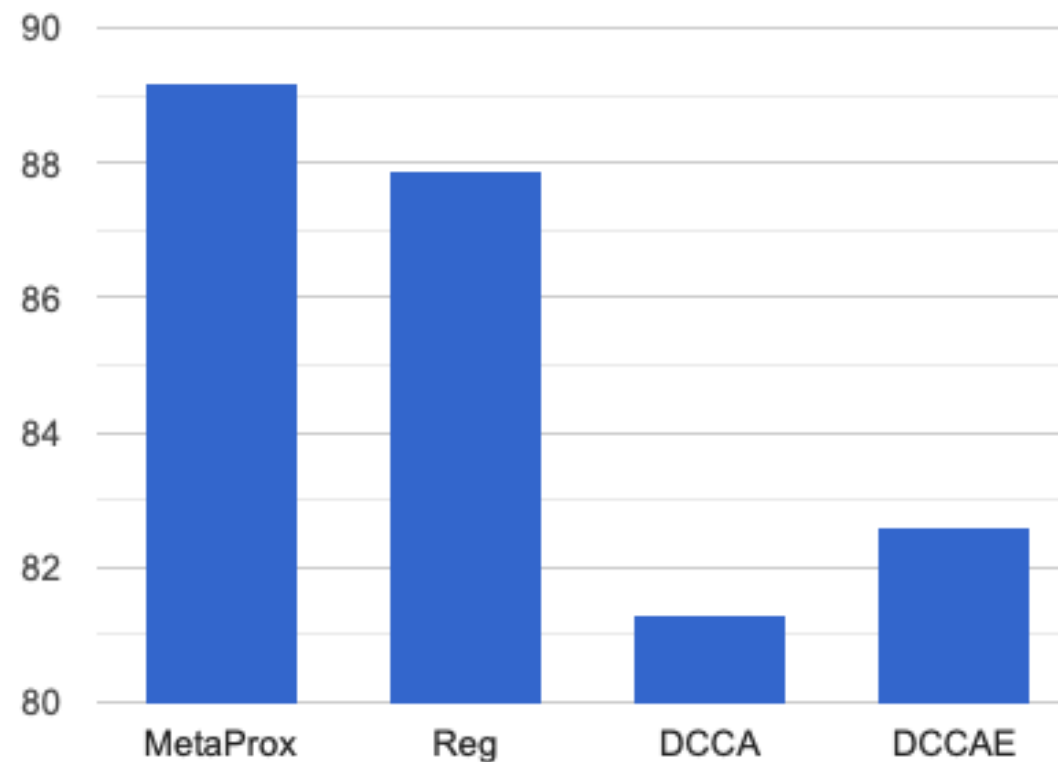
optimize over **red** variables

# Experiment Results

## Multi-view image classification

– **Dataset:** a subset of Sketchy (20 classes)

$\{(\text{img}, \text{sketch}), \text{'butterfly'}; \dots \dots; (\text{img}, \text{sketch}), \text{'cat'}\}$



Test accuracy for image classification



At the poster:  
More details and discussions

Thanks!

MetaProx  $\neq$

“Efficient Meta Learning via Minibatch  
Proximal Update” (NeurIPS 2019)

“Meta-Learning with Implicit Gradients”  
(NeurIPS 2019)

modeling

optimization